

Lecture 8: Roots of Equations – System of Nonlinear Equations

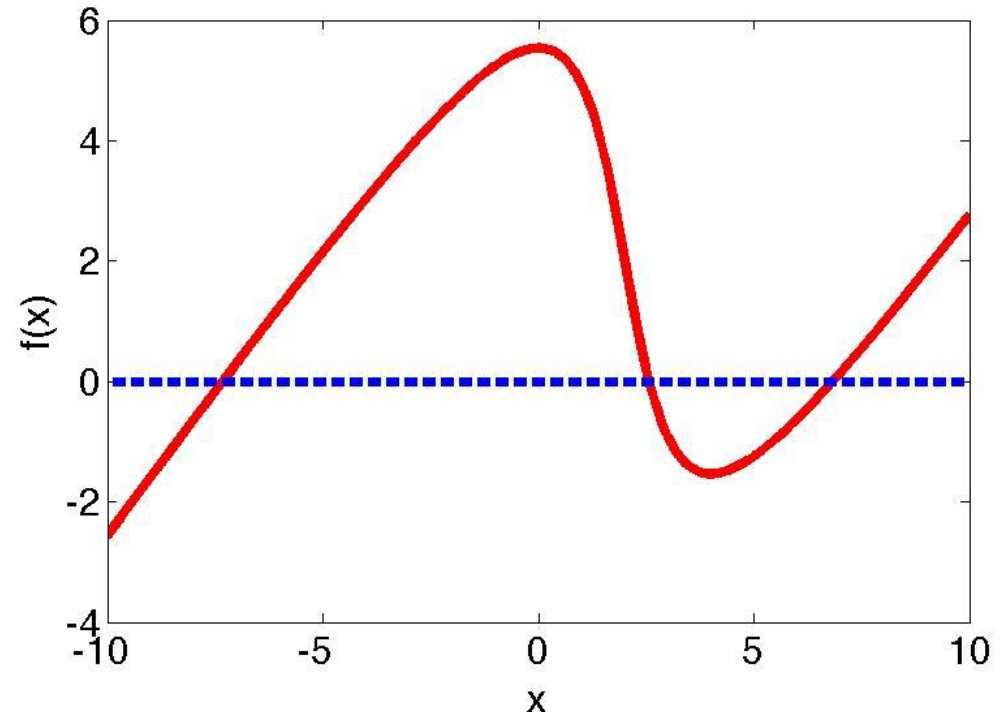
CBE 206

10.8.2019

Review of Open Methods: An Example: 1) Fixed-point Iteration

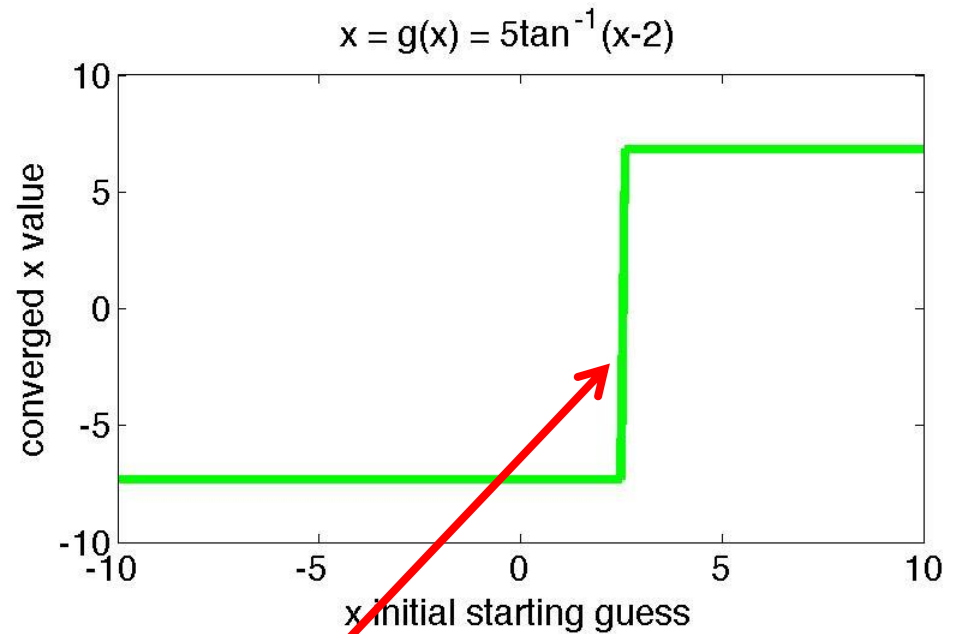
$$f(x) = x - 5 \tan^{-1}(x - 2)$$

- ▶ Plot this equation.
- ▶ We see that there are **three** solutions.
- ▶ Next, let us solve this problem using fixed point iteration.
- ▶ Let us reformulate this equation into $x = g(x) \rightarrow x = 5 \tan^{-1}(x - 2)$



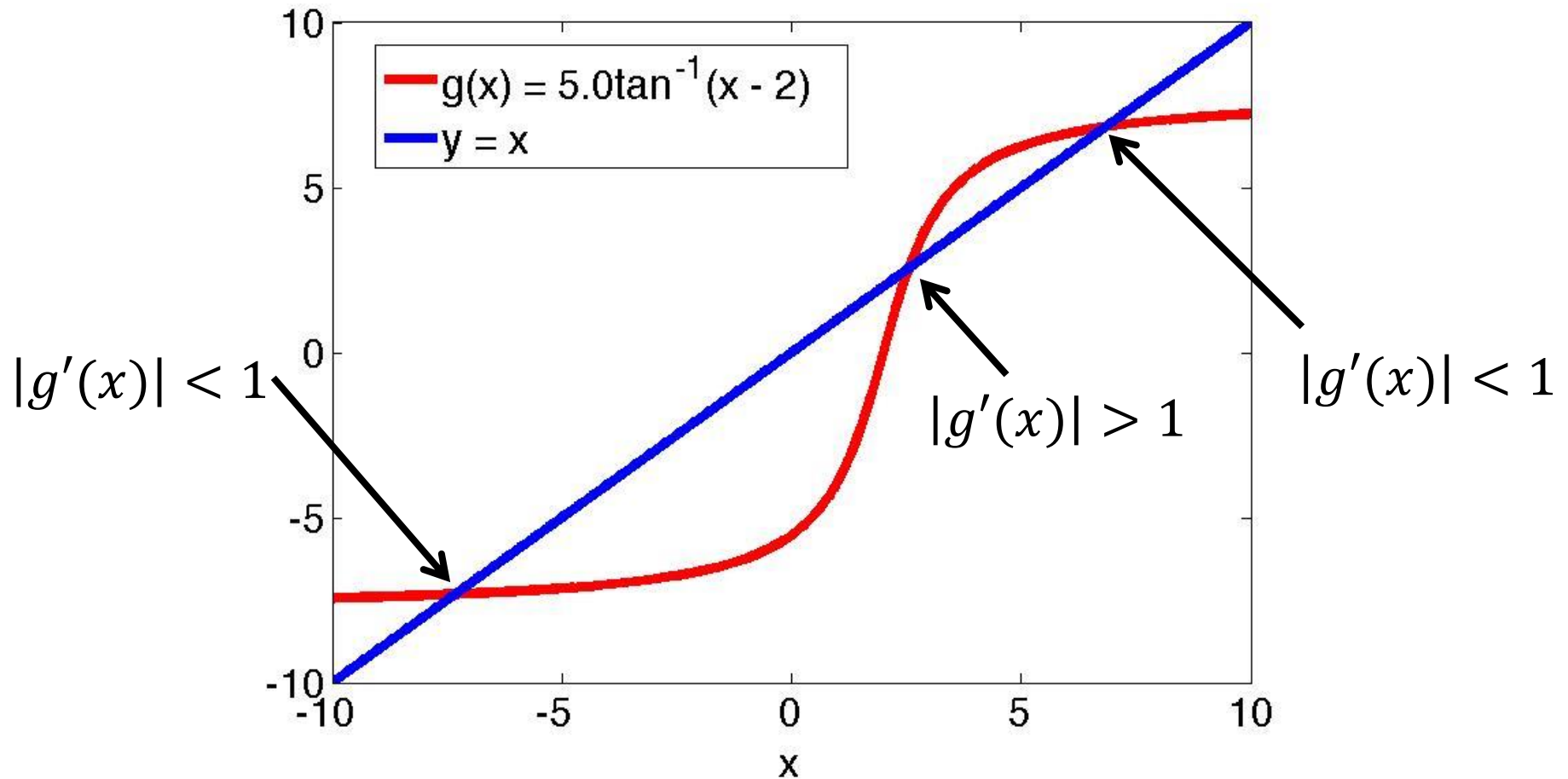
Review of Open Methods: An Example: 1) Fixed-point Iteration with Different Starting Guess

- ▶ Simple fixed point iteration method is used with 30 (no error threshold defined) different initial guess for x .
- ▶ One can see that we manage to obtain 2 out of the 3 roots ($x = -7.3195$ and $x = 6.8340$).
- ▶ Why can't we obtain the 3rd one?

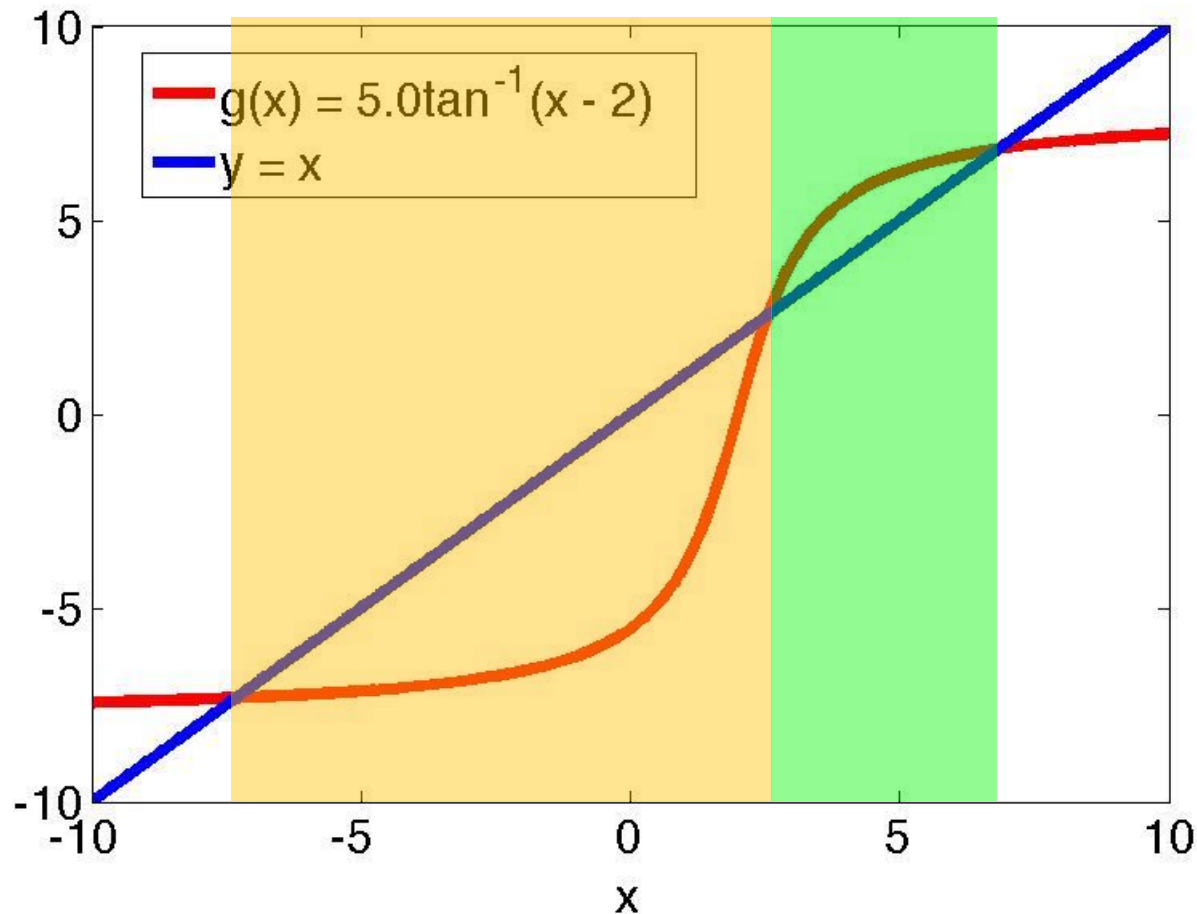


This discontinuity occurs where the 3rd solution is located!

Review of Open Methods: An Example: 1) Fixed-point Iteration $x = g(x)$, slopes



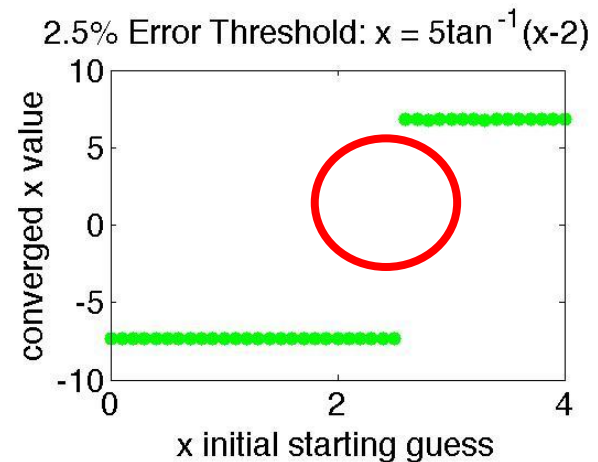
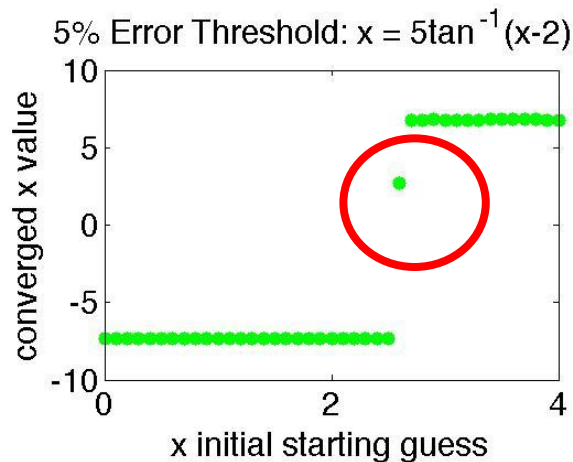
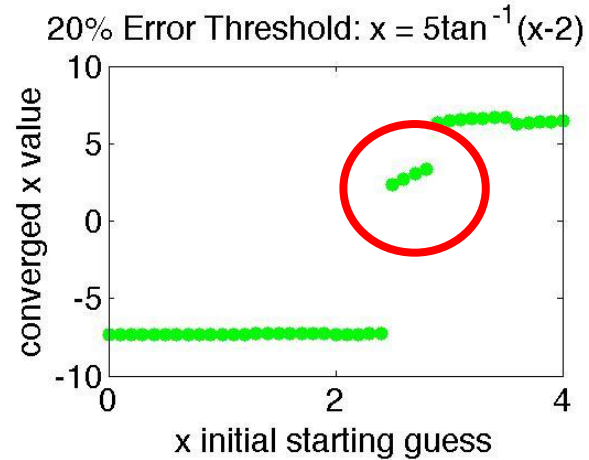
Review of Open Methods: An Example: 1) Fixed-point Iteration $x = g(x)$, Additional Interpretation



- ▶ In the green region, $g(x)$ is always larger than x .
- ▶ For any x chosen, the next choice of x (i.e. $g(x)$) is larger than the previous one.
- ▶ We move away from the solution at $x = 2.5$
- ▶ Similar argument for the yellow region.

Review of Open Methods: An Example: Repeat Slide 3 with Error Threshold

- ▶ In Slide 3, we obtained the convergent behavior for $N = 30$ iterations, without defining the error thresholds.
- ▶ For large error thresholds, we can get to the 3rd root since some of the initial guesses are good enough already.
- ▶ As error threshold decreases, the 3rd root disappears from our method.



Review of Open Methods: An Example: 2) Newton-Raphson Method

$$f(x) = x - 5 \tan^{-1}(x - 2)$$

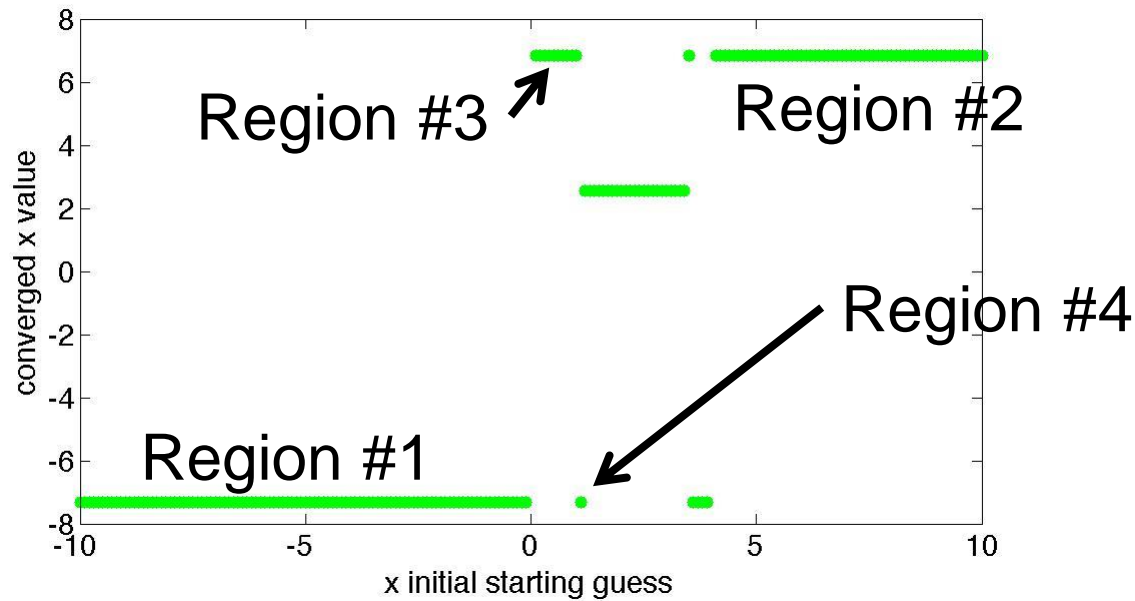
- ▶ For Newton-Raphson method, we need to compute the derivative of $f(x)$.

$$f'(x) = 1 - \frac{5}{1 + (x - 2)^2}$$

$$x_{i+1} = x_i - \frac{x_i - 5 \tan^{-1}(x_i - 2)}{1 - \frac{5}{1 + (x_i - 2)^2}}$$

Review of Open Methods: An Example: 2) Newton-Raphson Method with Different Starting Guess

- ▶ Newton-Raphson method is used with 30 different starting values of x .
- ▶ One can see that we manage to obtain all 3 out of the 3 solutions ($x = -7.3195$, $x = 2.5627$, and $x = 6.8340$).
- ▶ The initial starting x values that lead to the three solutions are not trivially predictable.



Review of Open Methods: An Example: 2) Newton-Raphson Method with Different Starting Guess

- ▶ At $x = 0$ and $x = 4$, the slope of $f(x)$ becomes zero (See Slide 2). i.e.

$$f'(x) = 1 - \frac{5}{1 + (x - 2)^2} \rightarrow f'(x) = 0 \text{ for } x = 0 \text{ and } 4$$

- ▶ With MATLAB (and other software), the Newton-Raphson method breaks down when the slope becomes zero since we are dividing by zero.
 - ▶ A good algorithm would check to see if $f'(x) = 0$.
 - ▶ What is happening elsewhere?
-

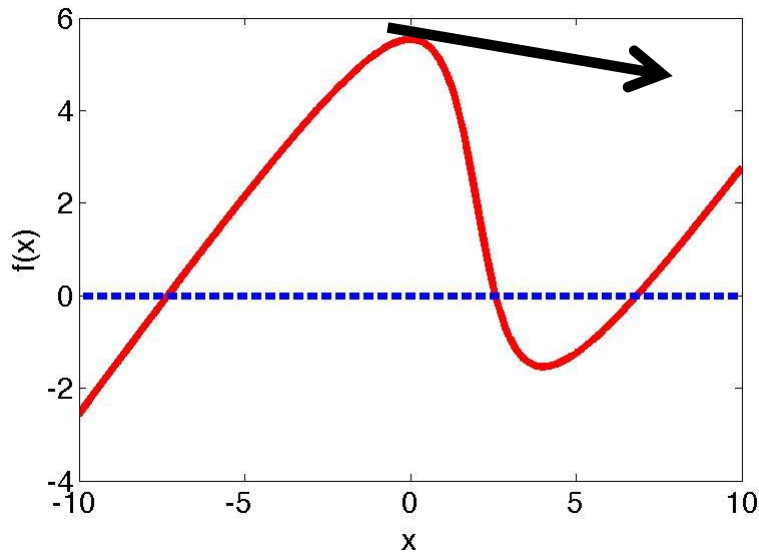
Region #1 $-10 < x < 0$: $f'(x) > 0 \rightarrow x_{i+1} > x_i$ when $f(x) < 0$ and $x_{i+1} < x_i$ when $f(x) > 0$ (move towards the correct direction for $x = -7.1395$ root).

Region #2 $4 < x < 10$: $f'(x) > 0 \rightarrow x_{i+1} > x_i$ when $f(x) < 0$ and $x_{i+1} < x_i$ when $f(x) > 0$ (move towards the correct direction for $x = 6.8340$ root).

Review of Open Methods: An Example: 2) Newton-Raphson Method with Different Starting Guess

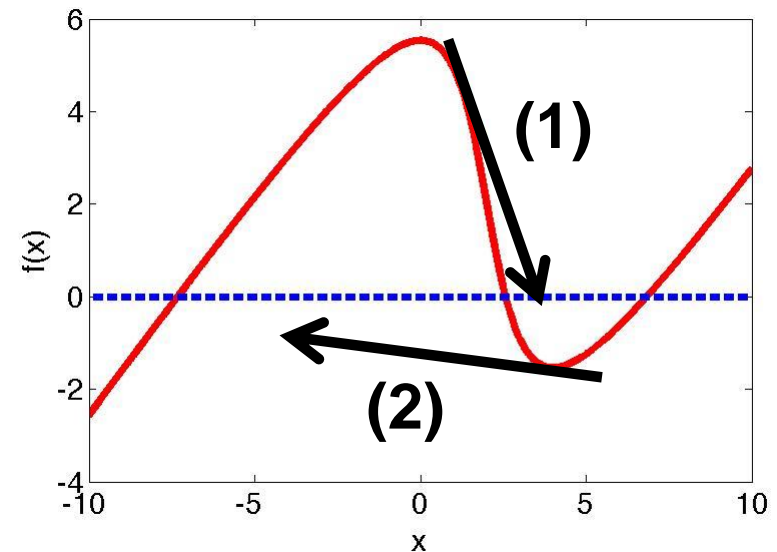
Region #3 $0 < x < 1.05$:

(Overshoot to right!!)



Region #4 $1.05 < x < 1.15$:

(Overshoot to left!!)



And so forth

System of **Nonlinear** Equations

- ▶ Thus, far we have solved **one** nonlinear equation with one unknown (i.e. $f(x) = 0$)
- ▶ We can solve a **system** of nonlinear equations with n equations and n unknowns.

$$f_1(x_1, x_2, \dots, x_n) = 0$$

$$f_2(x_1, x_2, \dots, x_n) = 0$$

.....

$$f_n(x_1, x_2, \dots, x_n) = 0$$

- ▶ In **Lecture 4** (Slide 2), we talked about system of **linear** equations.
- ▶ System of nonlinear equations is any set of equations that cannot be fitted into the form of linear equations.

System of Nonlinear Equations – Example 1

- ▶ Solving system of nonlinear equations is much more complicated than solving linear system of equations.
- ▶ Most methods use open methods (not bracket methods).
- ▶ Let us look at a simple example.

$$x^2 + xy = 10$$

$$y + 3xy^2 = 57$$

- ▶ First, check to see if this is linear or nonlinear...
- ▶ Fixed point iteration results in reformulating the equation to look like $x = g(x)$ in 1D. Now we need to do this for two different variables.
- ▶ The problem is, there are many ways to formulate this.
- ▶ Let us try one way.

Example 1: Fixed Point Iteration

$$x^2 + xy = 10 \rightarrow x = \frac{10 - x^2}{y} \rightarrow x_{i+1} = \frac{10 - x_i^2}{y_i}$$

$$y + 3xy^2 = 57 \rightarrow y = 57 - 3xy^2 \rightarrow y_{i+1} = 57 - 3x_{i+1}y_i^2$$

The correct answer is, $x = 2$ and $y = 3$. Assuming we know this, let us try a guess nearby: $x = 2.5$ and $y = 2.5$.

The approach:

- (1) Plug in $x = 2.5$ and $y = 2.5$ in the first equation. Get x_{new} .
- (2) Plug in x_{new} and $y = 2.5$ in the second equation. Get y_{new} .
- (3) Repeat this process until (hopefully) convergence.

Example 1: Fixed Point Iteration, Divergent Behavior

Iteration number	1 (initial guess)	2	3	4	5
x	2.5	3.0	9.333	0.0162	-0.3915
y	2.5	0.75	41.25	-25.500	820.763

The solution diverges!! What if we plug into the y equation first?

Iteration number	1 (initial guess)	2	3	4	5
y	2.5	10.125	-170.81	4801.8	-144780
x	2.5	0.7407	-0.0542	0.0021	-0.0001

Still diverges..

Example 1: Fixed Point Iteration, Reformulation

$$x^2 + xy = 10 \rightarrow x = \sqrt{10 - xy} \rightarrow x_{i+1} = \sqrt{10 - x_i y_i}$$

$$y + 3xy^2 = 57 \rightarrow y = \sqrt{\frac{57 - y}{3x}} \rightarrow y_{i+1} = \sqrt{\frac{57 - y_i}{3x_{i+1}}}$$

The solution converges!!

Iteration number	1 (initial guess)	2	3	4	5
x	2.5	1.9365	2.0171	1.9945	2.0019
y	2.5	3.0629	2.9855	3.0046	2.9985

It is difficult to predict a priori what is a good formulation that leads to convergence for system of equations. Thus, we will focus mostly on Newton-Raphson method.

Example Problem 1: Newton Raphson Method

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)} \quad \text{Newton-Raphson for one variable}$$

One can rearrange the equation in following format.

$$0 = f(x_i) + f'(x_i)(x_{i+1} - x_i)$$

In multi-dimensions, we have multiple functions, f_1, f_2, \dots, f_N with multiple variables x_1, x_2, \dots, x_N such that

$$f_1(x_1, x_2, \dots, x_N) = 0$$

$$f_2(x_1, x_2, \dots, x_N) = 0$$

$$\dots$$
$$f_N(x_1, x_2, \dots, x_N) = 0$$

Example Problem 1: Newton Raphson Method Setup

- ▶ We see that there are multiple variables (e.g. x_1, x_2, \dots, x_N).
- ▶ We use following notation: $x_{j,i} = j^{\text{th}}$ variable at i^{th} Newton Raphson iteration
- ▶ We need to use **partial derivatives** rather than ordinary derivatives here.
- ▶ Ordinary derivatives: $\frac{df}{dx}$ vs partial derivatives: $\frac{\partial f}{\partial x}$
- ▶ In partial derivatives, the function has several variables..
- ▶ Example: $f(x, y, z) \rightarrow \frac{\partial f}{\partial x}$ (y and z are constants), $\frac{\partial f}{\partial y}$ (x and z are constants)
- ▶ So going back to the formulation in the previous slide,

$$0 = f_1(x_{1,i}, x_{2,i}, \dots, x_{N,i}) + \sum_{j=1}^N \frac{\partial f_1}{\partial x_j} (x_{j,i+1} - x_{j,i})$$
$$0 = f_2(x_{1,i}, x_{2,i}, \dots, x_{N,i}) + \sum_{j=1}^N \frac{\partial f_2}{\partial x_j} (x_{j,i+1} - x_{j,i})$$

Example Problem 1: Newton Raphson Method Setup - Continued

- ▶ In 1D Newton Raphson method, we set $f(x_{i+1}) = 0$.
- ▶ We do the similar thing with the multi-dimension case here.

$$0 = f_1(x_{1,i}, x_{2,i}, \dots, x_{N,i}) + \sum_{j=1}^N \frac{\partial f_1}{\partial x_{j,i}} (x_{j,i+1} - x_{j,i})$$

...

- ▶ Writing in matrix form..

$$\begin{bmatrix} -f_1(x_{1,i}, x_{2,i}, \dots, x_{N,i}) \\ -f_2(x_{1,i}, x_{2,i}, \dots, x_{N,i}) \\ \dots \\ -f_N(x_{1,i}, x_{2,i}, \dots, x_{N,i}) \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1}{\partial x_{1,i}} & \frac{\partial f_1}{\partial x_{2,i}} & \dots & \frac{\partial f_1}{\partial x_{N,i}} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial f_N}{\partial x_{1,i}} & \frac{\partial f_N}{\partial x_{2,i}} & \dots & \frac{\partial f_N}{\partial x_{N,i}} \end{bmatrix} \begin{bmatrix} x_{1,i+1} - x_{1,i} \\ x_{2,i+1} - x_{2,i} \\ \dots \\ x_{N,i+1} - x_{N,i} \end{bmatrix}$$

Example Problem 1: Newton Raphson Method Setup - Continued

- ▶ This is confusing.. Let us look at what each of these terms represent.

$$\begin{bmatrix} -f_1(x_{1,i}, x_{2,i}, \dots, x_{N,i}) \\ -f_2(x_{1,i}, x_{2,i}, \dots, x_{N,i}) \\ \dots \\ -f_N(x_{1,i}, x_{2,i}, \dots, x_{N,i}) \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1}{\partial x_{1,i}} & \frac{\partial f_1}{\partial x_{2,i}} & \dots & \frac{\partial f_1}{\partial x_{N,i}} \\ \dots & \dots & \dots & \dots \\ \frac{\partial f_N}{\partial x_{1,i}} & \frac{\partial f_N}{\partial x_{2,i}} & \dots & \frac{\partial f_N}{\partial x_{N,i}} \end{bmatrix} \begin{bmatrix} x_{1,i+1} \\ x_{2,i+1} \\ \dots \\ x_{N,i+1} \end{bmatrix} - \begin{bmatrix} x_{1,i} \\ x_{2,i} \\ \dots \\ x_{N,i} \end{bmatrix}$$

Known from previous iteration

N nonlinear functions whose roots we are trying to obtain :
 f_1 : equation #1, f_2 : equation #2, ...
 $x_{1,i}$: 1st variable at i^{th} Newton-Raphson iteration.

$N \times N$ matrix of partial derivatives: **Jacobian** matrix.

Unknown. In a given Newton-Raphson iteration, this is what we are trying to solve.

Example Problem 1: Newton Raphson Method Setup - Continued

- ▶ Let us simplify notation.
- ▶ **Red box** from previous slide: $-\bar{f}(\bar{x}_i)$
- ▶ **Green box** from previous slide: $\bar{J}_f(\bar{x}_i)$
- ▶ **Blue** and **purple** boxes from previous slide: $(\overline{x_{i+1}} - \bar{x}_i)$
- ▶ So we have a nonlinear system of equations that looks as follows.

$$-\bar{f}(\bar{x}_i) = \bar{J}_f(\bar{x}_i)(\overline{x_{i+1}} - \bar{x}_i)$$

- ▶ We can take the inverse of the Jacobian and solve for $\overline{x_{i+1}}$.
- ▶ But in general, we do not like taking inverses..
- ▶ So we are going to solve a system of linear equations..
- ▶ Let $\bar{s}_i = (\overline{x_{i+1}} - \bar{x}_i)$. First, solve $\bar{J}_f(\bar{x}_i)\bar{s}_i = -\bar{f}(\bar{x}_i)$.
- ▶ Then, $\overline{x_{i+1}} = \bar{s}_i + \bar{x}_i$.

Newton-Raphson Algorithm for System of Nonlinear Equations

$\bar{x}_1 = \text{initial guess to the problem}$

Loop $i = 1, 2, 3, \dots$

Solve $\bar{J}_f(\bar{x}_i)\bar{s}_i = -\bar{f}(\bar{x}_i)$ for \bar{s}_i

$\bar{x}_{i+1} = \bar{s}_i + \bar{x}_i$

end

- ▶ Upon plugging in an initial guess to the equations, everything becomes linearized.
- ▶ Thus, we are essentially solving a system of linear equations at every iteration until we get convergence.
- ▶ Termination criterion varies, but in many cases, we can take the norm of the differences between \bar{x}_{i+1} and \bar{x}_i to see if it is smaller than some threshold.

Revisit Example from Slide 12: Newton-Raphson Algorithm for System of Nonlinear Equations

$$\begin{aligned}x^2 + xy &= 10 \\ y + 3xy^2 &= 57\end{aligned}$$



$$\begin{aligned}f_1(x, y) &= x^2 + xy - 10 = 0 \\ f_2(x, y) &= y + 3xy^2 - 57 = 0\end{aligned}$$

- ▶ Jacobian Matrix

$$J = \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix} = \begin{bmatrix} 2x + y & x \\ 3y^2 & 1 + 6xy \end{bmatrix}$$

- ▶ Initial guess (let's use the same guess as before): $x_1 = 2.5$; $y_1 = 2.5$;
 $f_1(x_1, y_1) = 2.5$; $f_2(x_1, y_1) = -7.625$

- ▶ New Jacobian matrix

$$J(x, y) = \begin{bmatrix} 2(2.5) + 2.5 & 2.5 \\ 3(2.5)^2 & 1 + 6(2.5)(2.5) \end{bmatrix} = \begin{bmatrix} 7.5 & 2.5 \\ 18.75 & 38.5 \end{bmatrix}$$

Revisit Example from Slide 12: Newton-Raphson Solution

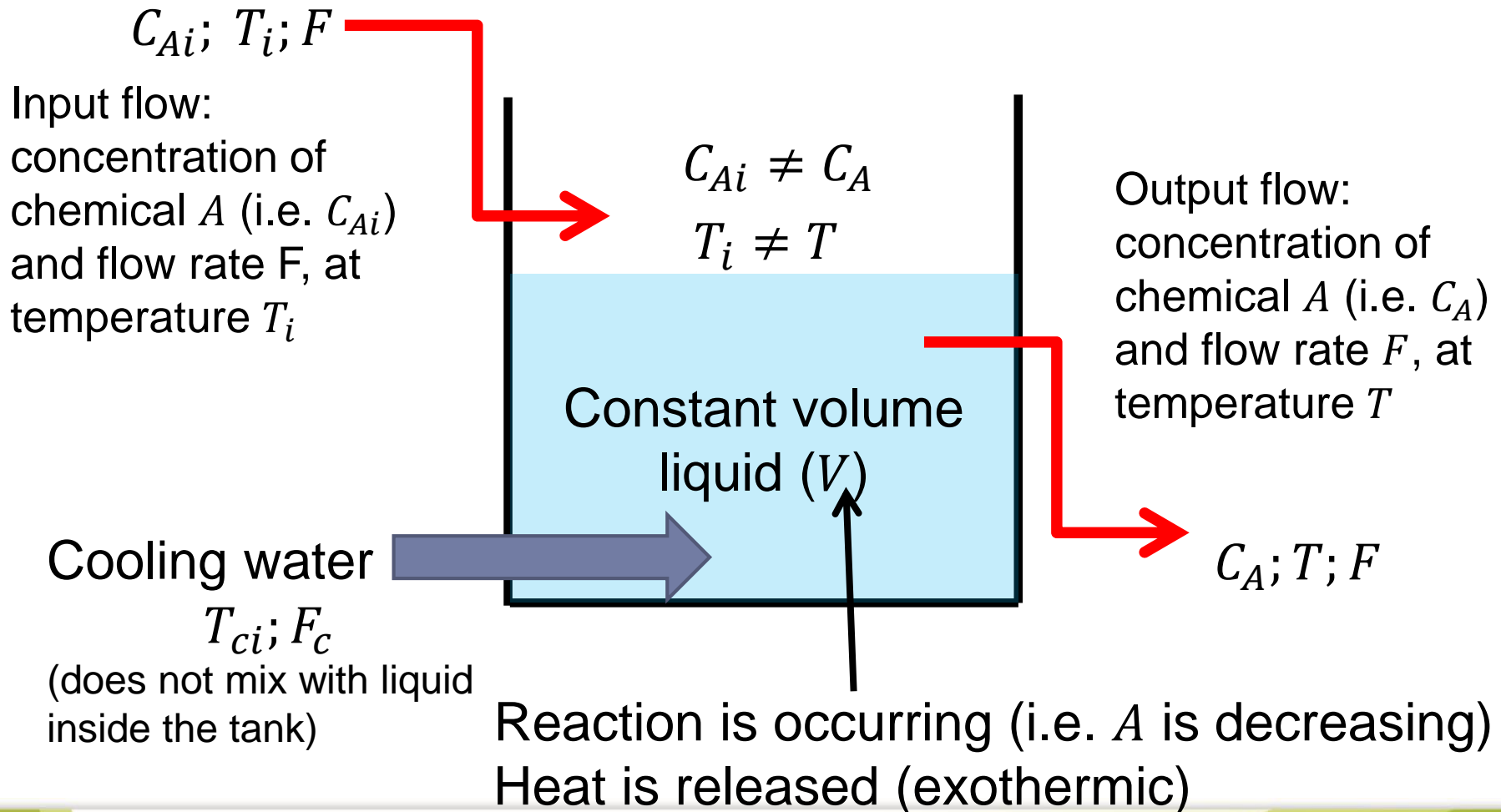
▶ 1st iteration:

$$\begin{bmatrix} 7.5 & 2.5 \\ 18.75 & 38.5 \end{bmatrix} \begin{bmatrix} s_1 \\ s_2 \end{bmatrix} = \begin{bmatrix} -2.5 \\ 7.625 \end{bmatrix} \rightarrow \begin{bmatrix} s_1 \\ s_2 \end{bmatrix} = \begin{bmatrix} -0.4767 \\ 0.4302 \end{bmatrix}$$

$$\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} s_1 \\ s_2 \end{bmatrix} + \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} 2.0233 \\ 2.9302 \end{bmatrix}$$

Iteration number	1 (initial guess)	2	3	4
y	2.5	2.0233	1.9998	2.0000
x	2.5	2.9302	3.0002	3.0000

Example 2: Tank Reactor: What is the Temperature and the Reactant Concentration in the Tank?



Tank Reactor: Materials Balance

Assume steady-state

$$0 = \{\text{rate of component "A" in}\} - \{\text{rate of component "A" out}\} + \{\text{rate of component "A" produced}\}$$

$$0 = FC_{Ai} - FC_A - Vr$$

$$r = kC_A = k_o e^{-\frac{E}{RT}} C_A$$

$$0 = FC_{Ai} - FC_A - V k_o e^{-\frac{E}{RT}} C_A$$

1st order reaction
(exponential decay)

Unknowns are C_A and T .

We need one more equation to solve for C_A and T

Tank Reactor: Energy Balance

Assume steady-state

$$0 = F\rho C_p T_i - F\rho C_p T - A(T - T_{ci}) - \Delta H_R V k_r C_A$$

Flux of heat
into the tank
(positive)

Flux of heat
coming out the
tank (negative)

Cooling
(negative)

Heat of reaction
(positive, $\Delta H_R < 0$)

Tank Reactor: Materials + Energy Balance

We plug in the data

$$F = \frac{1\text{m}^3}{\text{min}}; V = 1\text{m}^3; C_{Ai} = \frac{2.0\text{kmole}}{\text{m}^3}; T_i = 323\text{K}; C_p = 1\text{cal}/(\text{g K})$$

$$\rho = \frac{10^6\text{g}}{\text{m}^3}; k_o = 10^{10}\text{min}^{-1}; \frac{E}{R} = 8330.1\text{K}; \Delta H_R = -1.3 \times \frac{10^8\text{cal}}{\text{kmole}};$$
$$T_{ci} = 365\text{K}; A = 5.3417 \times 10^6\text{cal}/(\text{K min})$$

Materials Balance

$$0 = 2 - C_A - 10^{10} e^{\frac{-8330.1}{T}} C_A$$

Energy Balance

$$0 = 3.23 \times 10^8 - 10^6 T - 5.3417 \times 10^6 (T - 365) + 1.3 \times 10^{18} e^{\frac{-8330.1}{T}} C_A$$
$$0 = 323 - T - 5.3417 (T - 365) + 1.3 \times 10^{12} e^{\frac{-8330.1}{T}} C_A$$

Newton-Raphson Algorithm for System of Nonlinear Equations

$$f_1(T, C_A) = 2 - C_A - 10^{10} e^{-\frac{8330.1}{T}} C_A = 0$$

$$f_2(T, C_A) = 323 - T - 5.3417(T - 365) + 1.3 \times 10^{12} e^{-\frac{8330.1}{T}} C_A$$

▶ Jacobian Matrix

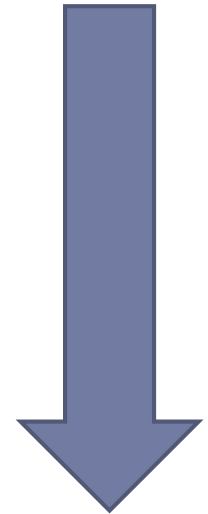
$$J = \begin{bmatrix} \frac{\partial f_1}{\partial T} & \frac{\partial f_1}{\partial C_A} \\ \frac{\partial f_2}{\partial T} & \frac{\partial f_2}{\partial C_A} \end{bmatrix} = \begin{bmatrix} -8.3301 \times 10^{13} e^{-\frac{8330.1}{T}} \frac{C_A}{T^2} & -1 - 10^{10} e^{-\frac{8330.1}{T}} \\ -1 - 5.3417 + 1.0829 \times 10^{16} e^{-\frac{8330.1}{T}} \frac{C_A}{T^2} & 1.3 \times 10^{12} e^{-\frac{8330.1}{T}} \end{bmatrix}$$

▶ Initial Guess

Let us choose, $C_A = C_{Ai} = \frac{2 \text{ kmole}}{\text{m}^3}$ and $T = T_{cin} = 365 \text{ K}$

Newton-Raphson Algorithm Results

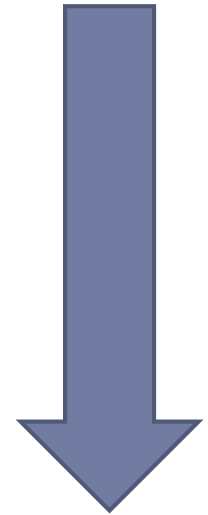
Iteration Number	T (Kelvin)	C_A (kmole/m ³)	f_1	f_2
1 (initial guess)	365	2	-2.4518	276.7289
2	326.2495	3.5673	-1.8581	241.5433
3	388.1774	0.5463	-1.1623	151.1046
4	396.6136	0.1347	0.8468	-110.0878
5	394.2850	0.2483	0.0934	-12.1432
6	393.9580	0.2643	0.0016	-0.2109
7	393.9521	0.2646	5.17e-07	-6.8e-05
8	393.9521	0.2646	5.53e-14	-3.1e-10



Converging Behavior!!!

Newton-Raphson Algorithm Results: Not All is Well Depending on the Initial Guess

Iteration Number	T (Kelvin)	C_A (kmole/m ³)	f_1	f_2
1 (initial guess)	323 (= T_i)	2	-0.1261	240.7427
2	369.9165	1.4371	-1.8230	236.9948
3	252.0485	7.1872	-5.1875	674.3458
4	358.4701	1.9955	-1.6096	209.2500
5	260.2790	6.7856	-4.7864	622.2206
6	358.5943	1.9894	-1.6117	209.5158
7	261.0729	6.7469	-4.7478	617.1964
8	358.6119	1.9885	-1.6120	209.5536



Oscillating Behavior!!!

Not converging!!

Exothermic Tank Reactor: Plotting Temperature

- ▶ This system of nonlinear equations is simple enough such that we can eliminate one variable (i.e. C_A) analytically.
- ▶ From materials balance equation..

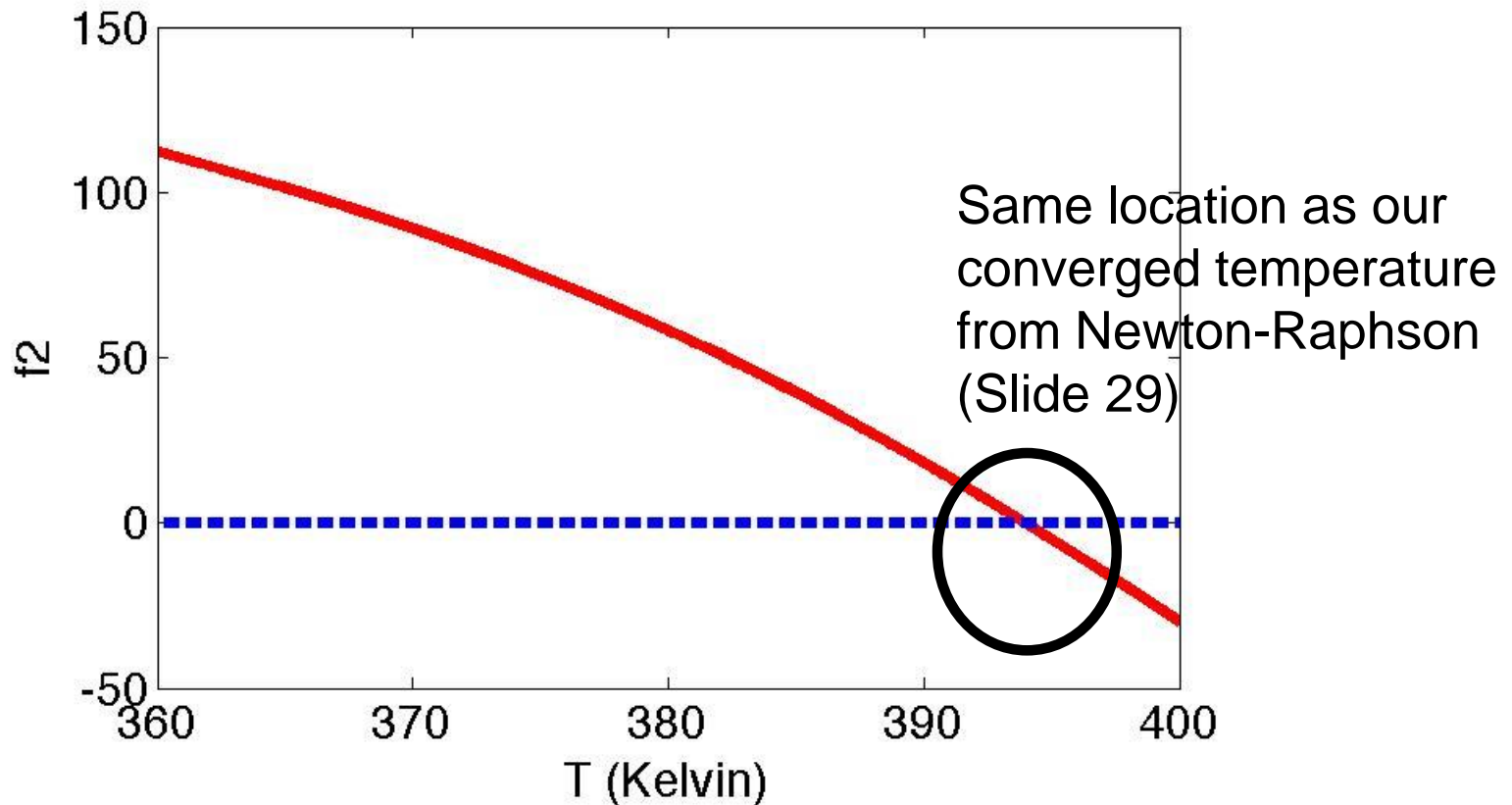
$$f_1(T, C_A) = 2 - C_A - 10^{10} e^{-\frac{8330.1}{T}} C_A = 0$$

$$C_A = \frac{2}{(1 + 10^{10} e^{-\frac{8330.1}{T}})}$$

- ▶ Plug C_A into the energy balance equation and plot

$$f_2(T, C_A) = 323 - T - 5.3417(T - 365) + 1.3 \times 10^{12} e^{-\frac{8330.1}{T}} C_A$$

Tank Reactor: Plotting Temperature



- ▶ You can obtain C_A from the T value above.
- ▶ In general, solving system of nonlinear equations is not so easy such that you can isolate for individual variables. Need to use numerical methods.

Tank Reactor: Changes in the Input Parameters

We plug in the **new** data

$$F = \frac{1\text{m}^3}{\text{min}}; V = 1\text{m}^3; C_{Ai} = \frac{2.0\text{kmole}}{\text{m}^3}; T_i = 343\text{K}; C_p = 1\text{cal}/(\text{g K})$$

$$\rho = \frac{10^6\text{g}}{\text{m}^3}; k_o = 10^{10}\text{min}^{-1}; \frac{E}{R} = 8330.1\text{K}; \Delta H_R = -1.3 \times \frac{10^8\text{cal}}{\text{kmole}};$$
$$T_{ci} = 310\text{K}; A = 1.8736 \times 10^6\text{cal}/(\text{K min})$$

$$f_1(T, C_A) = 2 - C_A - 10^{10}e^{-\frac{8330.1}{T}}C_A = 0 \quad (\text{same})$$

$$f_2(T, C_A) = 343 - T - 1.8736(T - 310) + 1.3 \times 10^{12}e^{-\frac{8330.1}{T}}C_A$$

You can try to compute the Jacobian matrix yourself.

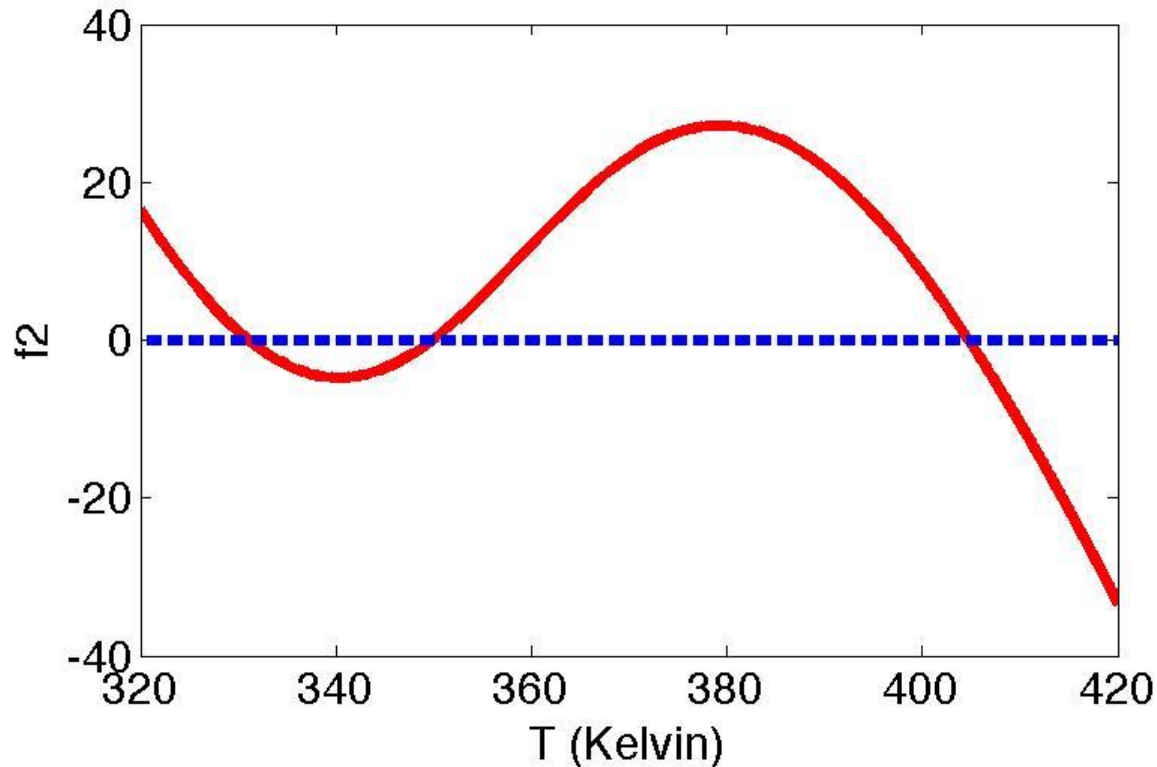
Tank Reactor: Changes in the Input Parameters

Yield Multiple Solutions

Iteration Number	T (Kelvin)	C_A (kmole/m ³)	T (Kelvin)	C_A (kmole/m ³)	T (Kelvin)	C_A (kmole/m ³)
1	300	2	350	2	400	2
2	324.0064	1.9442	349.9662	1.3704	407.8040	0.2845
3	329.8970	1.8140	349.9032	1.3718	405.1967	0.0919
4	330.9634	1.7905	349.9029	1.3718	404.7500	0.1496
5	331.0092	1.7894	349.9029	1.3718	404.7380	0.1594
6	331.0093	1.7894	349.9029	1.3718	404.7380	0.1597

3 sets of solutions.. All valid mathematically.

Tank Reactor: Plotting Temperature for New Input



- ▶ In general, system of nonlinear equations have multiple solutions.
- ▶ Newton-Raphson method in this case can find all three set of solutions.

Summary

- ▶ System of nonlinear equations are very difficult to solve by hand.
- ▶ We can use the open methods (preferably Newton-Raphson over fixed-point iteration) to numerically solve the system of nonlinear equations.
- ▶ We should always check to see whether the Newton-Raphson algorithm leads to correct solutions (in many cases, it does not).
- ▶ We can try different starting guesses to see the convergent behaviors.
- ▶ In engineering, it is always important to make sure if the values we obtain makes sense physically (not just mathematically).

Homework #3 Due 10/17 Thursday Before 10:30 AM

- ▶ In this assignment you will code your version of system of nonlinear equations.
- ▶ You will turn in three m files:
 - ▶ CBE206_hw3_studentID.m
- ▶ In the file, you will write the solution to example 1 (Lecture 8, Slide 12). This function will take two input variables x_1 , and y_1 .

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- ▶ For the example, we will make usage of symbolic differentiation in MATLAB.

- ▶ Example:

```
clear all;
```

```
syms x y % declare x and y to be variables in symbols to use
```

```
f(x,y) = x + cos(y) % now you can use x and y as variables
```

```
df_dx(x,y) = diff(f,x) % you can differentiate f(x,y) with respect to variable x
```

```
df_dy(x,y) = diff(f,y) % you can differentiate f(x,y) with respect to variable y
```

```
a = double(df_dx(1,1)) % you can plug in specific x and y values to df_dx to get the value. Keyword "double" is used to go from the symbol to actual numerical values that we can use
```

```
b = double(df_dy(1,-2)) % similar to above
```

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- ▶ There are two sets of solutions for this problem: (x_{1_sol}, y_{1_sol}) and (x_{2_sol}, y_{2_sol})
- ▶ You will construct an outer loop that finds all these two solutions with initial random guesses for $x \rightarrow [-5, 5]$ and $y \rightarrow [-5, 5]$
- ▶ The Newton-Raphson algorithm loop will continue until the norm is less than $1e-5$. Where, norm is defined as follows: $n = \sqrt{(\bar{s}_i)^2}$
- ▶ If the Newton-Raphson algorithm does not converge after 100 iterations, we will stop and terminate the loop.
- ▶ For the system of linear equations part, you should use the algorithm we learned for the Gaussian elimination section.
- ▶ You shouldn't print out duplicate solutions.. So only two sets of solutions (one for first solution and one for second solution) should be printed out (see next page).

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▶ Sample output: (the real solutions are not included below)

>> CBE206_hw3_studentID

```
my initial guesses are 0.688237 and -0.306094
my 1th iteration norm = 150.958974
my 2th iteration norm = 51.475145
my 3th iteration norm = 33.528067
my 4th iteration norm = 22.606942
my 5th iteration norm = 15.158048
my 6th iteration norm = 10.106712
my 7th iteration norm = 6.688932
my 8th iteration norm = 4.358628
my 9th iteration norm = 2.728125
my 10th iteration norm = 1.525711
my 11th iteration norm = 0.622189
my 12th iteration norm = 0.113876
my 13th iteration norm = 0.003725
my 14th iteration norm = 0.000004
my solutions are x1_sol and y1_sol
```

```
my initial guesses are -4.880979 and -1.628774
my 1th iteration norm = 2.140872
my 2th iteration norm = 19.846354
my 3th iteration norm = 26.060261
my 4th iteration norm = 8.544744
my 5th iteration norm = 3.918265
my 6th iteration norm = 1.543379
my 7th iteration norm = 0.464519
my 8th iteration norm = 0.077482
my 9th iteration norm = 0.001295
my 10th iteration norm = 0.000000
my solutions are x2_sol and y2_sol
```


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- ▶ You will be graded on following aspects of the code.
- ▶ No error in executing your file
- ▶ Obtain both solutions correctly
- ▶ Print out the norm values for each iteration
- ▶ Print out only two unique solutions (do not print more than two)